Eigenvalue shap optimization

Main results

EIGENVALUE PROBLEMS AND FREE BOUNDARY MINIMAL SURFACES IN SPHERICAL CAPS

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(Joint work with Ana Menezes - Princeton University)

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Free Boundary Minimal Surfaces

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Definition

Consider a Riemannian manifold with boundary $(\mathcal{N}^n, \mathbf{g})$ and a compact surface Σ^2 . Let $\Phi : \Sigma \to \mathcal{N}$ be an immersion such that $\Phi(\Sigma) \cap \partial \mathcal{N} = \Phi(\partial \Sigma)$.

• Φ is a free boundary minimal immersion if: (i) $\vec{H} = 0$;

(ii) $\Phi(\Sigma)$ meets $\partial \mathcal{N}$ orthogonally along $\Phi(\partial \Sigma)$ (i.e., $\nu \perp \partial \mathcal{N}$).

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Remark: If $\partial \Sigma = \emptyset$ we say Φ is a closed minimal immersion.

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Figure: $(\mathcal{N}, \mathbf{g}) =$ Euclidean 3-ball and $\Phi(\Sigma) =$ equatorial disc.

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Critical Points of the Area Functional with Free Boundary

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Critical Points of the Area Functional with Free Boundary

- Let Φ_t : Σ → N be a smooth one parameter family of immersions for t ∈ (-ε, ε) such that Φ_t(∂Σ) ⊂ ∂N.
- Denote $X = \frac{\partial \Phi}{\partial t} (X|_{\partial \Sigma}$ is tangent to $\partial \mathcal{N}$).



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The first variation formula gives:

$$\frac{d}{dt}\Big|_{t=0} |\Phi_t(\Sigma)| = -\int_{\Sigma} \langle \vec{H}, X \rangle \, dA + \int_{\partial \Sigma} \langle \nu, X \rangle \, dL.$$

Critical point $\iff \vec{H} = 0$ and $\nu \perp \partial \mathcal{N}.$

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- (*M*, *g*) closed Riemannian surface;
- Laplacian of (M,g): $\Delta_g = \operatorname{div}_g(\nabla_g) : C^\infty(M) \to C^\infty(M);$

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i.e., ϕ_j is a eigenfunction of $-\Delta_g$ with eigenvalue 2.

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The normalized first Laplacian eigenvalue

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The normalized first Laplacian eigenvalue

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In a closed surface M we can consider:

$$\lambda_1^*(M) = \sup_g \lambda_1(g) |M|_g.$$

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The maximizer induces a harmonic map $\phi : (M, \mathcal{C}) \to \mathbb{S}^n$.

• (Karpukhin-Kusner-Mcgrath-Stern, new preprint-2024): Let M_{γ} be the closed orientable surface of genus γ . Then $\lambda_1^*(M_{\gamma})$ or $\lambda_1^*(M_{\gamma+1})$ admits a maximizing metric, for each γ .

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• 2-sphere (Hersch, 1970): round metric, $\mathrm{Id}: \mathbb{S}^2 \to \mathbb{S}^2$, $\lambda_1^* = 8\pi$;

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- Projective plane (Li-Yau, 1982): round metric, Veronese immersion ℝP² → S⁵, λ₁^{*} = 12π;

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- 2-torus (Nadirashvili, 1996): flat equilateral metric, unique immersion by first eigenfunctions, T² → S⁵, λ₁^{*} = ^{8π²}/_{√3};

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- Klein bottle (El Soufi-Giacomini-Jazar, Jakobson-Nadirashvili-Polterovich, 2006): there is a unique immersion by first eigenfunctions K → S⁴, λ₁^{*} = 12πE(^{2√2}/₃);

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- Orientable surface of genus 2 (Nayatani-Shoda, 2019): induced by a certain branched cover M → S², λ₁^{*} = 16π.

Free-boundary minimal immersions and Steklov eigenvalues

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Free-boundary minimal immersions and Steklov eigenvalues

• (Σ, g) - compact Riemannian surface, with non-empty boundary;

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• ν - outward pointing *g*-unit conormal vector field on $\partial \Sigma$.

Free-boundary minimal immersions and Steklov eigenvalues

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Eigenvalue shape

• Dirichlet-to-Neumann map of (Σ, g) : $S_g : C^{\infty}(\partial \Sigma) \to C^{\infty}(\partial \Sigma)$,

$$S_{g}\phi = \frac{\partial \widehat{\phi}}{\partial \nu},$$

where $\hat{\phi}$ is the harmonic extension of ϕ ($\Delta_g \hat{\phi} = 0$).

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The normalized first Steklov eigenvalue

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The normalized first Steklov eigenvalue

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Main results

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The maximizer induces a free-boundary harmonic map $\phi: (\Sigma, \mathcal{C}) \to B^n$.

 (Karpukhin-Kusner-Mcgrath-Stern, new preprint-2024): each compact oriented surface with boundary, of genus zero or one, admits a σ₁^{*}-maximizing metric.

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Main results

• Disk (Weinstock, 1954): Flat metric with c.g.c, $\mathrm{Id}: \mathsf{B}^2 \to \mathsf{B}^2$, $\sigma_1^* = 2\pi$.

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- Disk (Weinstock, 1954): Flat metric with c.g.c, $\mathrm{Id}: \mathsf{B}^2 \to \mathsf{B}^2$, $\sigma_1^* = 2\pi$.
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- Orientable surface of genus 0 and ℓ boundary components (Fraser-Schoen, 2012 + Karpukhin-Stern, 2021): σ₁^{*} is realized by an embedded FBMS Σ_ℓ ⊂ B³, such that Σ_ℓ → S² as ℓ → ∞.

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Figure: Picture by M. Schulz.

Minimal Surface

Eigenvalue shap optimization





Main results

 $\mathbb{B}_r^n = \{ x \in \mathbb{S}^n; x_0 \ge \cos r \} :$ geodesic ball of \mathbb{S}^n of center $p = (1, 0, \dots, 0)$ and radius $0 < r < \pi/2.$

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• $\Phi : (\Sigma, g) \to \mathbb{B}^n_r$ is minimal and free boundary if, and only if, $\phi_i = x_i \circ \Phi$ satisfy:

$$\begin{aligned} -\Delta_g \phi_i &= 2\phi_i, \quad \text{in } \Sigma, \ i = 0, 1, \dots, n, \\ \frac{\partial \phi_0}{\partial \nu} &= -(\tan r)\phi_0, \quad \text{on } \partial \Sigma, \\ \frac{\partial \phi_i}{\partial \nu} &= (\cot r)\phi_i, \quad \text{on } \partial \Sigma, \ i = 1, \dots, n. \end{aligned}$$

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Free Boundary Minimal Surface

Eigenvalue shap optimization

 x_1^{\leftarrow}



• $\sigma = 2$ is not an eigenvalue of $-\Delta_g$ with Dirichlet boundary condition:

$$\begin{cases} -\Delta_g w = 2w, & \text{in } \Sigma, \Rightarrow w \equiv 0. \\ w = 0, & \text{on } \partial \Sigma, \end{cases}$$

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Free Boundary Minimal Surfaces

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Main results

- Fix $\alpha \in \mathbb{R}$ which is not on the spectrum of $-\Delta_g$ with Dirichlet boundary condition;
- given $u \in C^{\infty}(\partial \Sigma)$, there is a unique $\widehat{u} \in C^{\infty}(\Sigma)$, such that

$$\Delta_{g} \widehat{u} + \alpha \widehat{u} = 0, \quad \text{in } \Sigma,$$
$$\widehat{u} = u, \quad \text{in } \partial \Sigma.$$

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• Dirichlet-to-Neumann map at frequency α :

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u}. \end{array}$$

• The spectrum of \mathcal{D}_{α} is discrete (Steklov eigenvalues with frequency α)

$$\sigma_0(g, \alpha) < \sigma_1(g, \alpha) \leq \sigma_2(g, \alpha) \leq \cdots \rightarrow +\infty.$$

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- Fix α ∈ ℝ which is not on the spectrum of −Δ_g with Dirichlet boundary condition;
- given $u \in C^{\infty}(\partial \Sigma)$, there is a unique $\widehat{u} \in C^{\infty}(\Sigma)$, such that

$$\Delta_{g}\widehat{u} + \alpha \widehat{u} = 0, \quad \text{in } \Sigma,$$
$$\widehat{u} = u, \quad \text{in } \partial \Sigma.$$

• Dirichlet-to-Neumann map at frequency α :

$$egin{array}{rcl} \mathcal{D}_lpha:\mathcal{C}^\infty(\partial\Sigma)& o&\mathcal{C}^\infty(\partial\Sigma)\ &&\mathcal{D}_lpha\phi&=&rac{\partial\widehat\phi}{\partial
u}. \end{array}$$

• The spectrum of \mathcal{D}_{α} is discrete (Steklov eigenvalues with frequency α)

$$\sigma_0(g, \alpha) < \sigma_1(g, \alpha) \leq \sigma_2(g, \alpha) \leq \cdots \rightarrow +\infty.$$

• The case $\alpha = 0$ corresponds to the usual Steklov spectrum.

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Variational characterization of eigenvalues

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Free Boundary Minimal Surface

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Variational characterization of eigenvalues

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Main results

The eigenvalue $\sigma_0(g, \alpha)$ is simple and is given by

$$\sigma_{0}(g,\alpha) = \inf \left\{ \frac{\int_{\Sigma} |\nabla^{g} \widehat{u}|_{g}^{2} dA_{g} - \alpha \int_{\Sigma} \widehat{u}^{2} dA_{g}}{\int_{\partial \Sigma} u^{2} dL_{g}}; u \in \operatorname{dom}(\mathcal{D}_{\alpha}) \setminus \{0\} \right\}.$$

Variational characterization of eigenvalues

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Denote by ϕ_{0} a first eigenfunction, which we can choose to be positive. Then,

$$\sigma_{1}(g,\alpha) = \inf \left\{ \frac{\int_{\Sigma} |\nabla^{g} \widehat{u}|_{g}^{2} dA_{g} - \alpha \int_{\Sigma} \widehat{u}^{2} dA_{g}}{\int_{\partial \Sigma} u^{2} dL_{g}}; u \in \operatorname{dom}(\mathcal{D}_{\alpha}) \setminus \{0\} \right.$$

and
$$\int_{\partial \Sigma} u\phi_{0} dL_{g} = 0 \left. \right\}.$$

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Free Boundary Minimal Surface

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Main results

• Σ - compact orientable surface of genus γ and ℓ boundary components;

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- Σ compact orientable surface of genus γ and ℓ boundary components;
- $\mathcal{M}(\Sigma)$ space of smooth Riemannian metrics g on Σ such that 2 is not an eigenvalue of $-\Delta_g$ with Dirichlet boundary condition;

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Free Boundary Minimal Surfaces

Eigenvalue shape optimization

- Σ compact orientable surface of genus γ and ℓ boundary components;
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Free Boundary Minimal Surfaces

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- Along $\partial \Sigma$ it holds

$$u_0 = \cos r$$
, $u_1^2 + u_2^2 = \sin^2 r$.

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• By using conformal diffeomorphisms of \mathbb{B}^2_r , we can assume

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$$\int_{\partial \Sigma} u_j \phi_0 \, dL = 0, \quad j = 1, 2,$$

where ϕ_0 is a positive eigenfunction associated to $\sigma_0(g, 2)$.

$$\begin{split} \sigma_0(g,2)\int_{\partial\Sigma} u_0^2\,dL_g &\leq \int_{\Sigma} |\nabla^g\,\widehat{u}_0|_g^2\,dA_g - 2\int_{\Sigma} \widehat{u}_0^2\,dA_g \\ &\leq \int_{\Sigma} |\nabla^g\,u_0|_g^2\,dA_g - 2\int_{\Sigma} u_0^2\,dA_g, \end{split}$$

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$$\begin{split} \sigma_0(g,2) \int_{\partial \Sigma} u_0^2 \, dL_g &\leq \int_{\Sigma} |\nabla^g \widehat{u}_0|_g^2 \, dA_g - 2 \int_{\Sigma} \widehat{u}_0^2 \, dA_g \\ &\leq \int_{\Sigma} |\nabla^g u_0|_g^2 \, dA_g - 2 \int_{\Sigma} u_0^2 \, dA_g, \end{split}$$

and for
$$j = 1, 2,$$

$$\begin{aligned} \sigma_1(g,2) \int_{\partial \Sigma} u_j^2 \, dL_g &\leq \int_{\Sigma} |\nabla^g \, \widehat{u}_j|_g^2 \, dA_g - 2 \int_{\Sigma} \widehat{u}_j^2 \, dA_g \\ &\leq \int_{\Sigma} |\nabla^g \, u_j|_g^2 \, dA_g - 2 \int_{\Sigma} u_j^2 \, dA_g. \end{aligned}$$

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$$\sigma_0(g,2)\int_{\partial\Sigma} u_0^2 dL_g \leq \int_{\Sigma} |\nabla^g \widehat{u}_0|_g^2 dA_g - 2\int_{\Sigma} \widehat{u}_0^2 dA_g$$
$$\leq \int_{\Sigma} |\nabla^g u_0|_g^2 dA_g - 2\int_{\Sigma} u_0^2 dA_g,$$

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We obtain

 $\left(\sigma_0(g,2)\cos^2 r + \sigma_1(g,2)\sin^2 r\right)|\partial\Sigma|_g + 2|\Sigma|_g \leq 4\pi(1-\cos r)(\gamma+\ell).$

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$$\begin{aligned} \sigma_0(g,2) \int_{\partial \Sigma} u_0^2 \, dL_g &\leq \int_{\Sigma} |\nabla^g \widehat{u}_0|_g^2 \, dA_g - 2 \int_{\Sigma} \widehat{u}_0^2 \, dA_g \\ &\leq \int_{\Sigma} |\nabla^g u_0|_g^2 \, dA_g - 2 \int_{\Sigma} u_0^2 \, dA_g, \end{aligned}$$

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We define

 $\Theta_r(\Sigma,g) = \left(\sigma_0(g,2)\cos^2 r + \sigma_1(g,2)\sin^2 r\right)|\partial\Sigma|_g + 2|\Sigma|_g.$

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Main results I

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Theorem A (L., Menezes, 2023)

Let Σ be a compact orientable surface of genus γ and ℓ boundary components. Then, for any $g \in \mathcal{M}(\Sigma)$, we have

$$\Theta_r(\Sigma,g) \leq 4\pi(1-\cos r)(\gamma+\ell).$$

Moreover, if Σ is a disk, the equality holds if, and only if, (Σ, g) is isometric to \mathbb{B}^2_r .

Therefore $\Theta_r^*(\Sigma) = \sup_{g \in \mathcal{M}(\Sigma)} \Theta_r(\Sigma, g)$ is finite.

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Therefore $\Theta_r^*(\Sigma) = \sup_{g \in \mathcal{M}(\Sigma)} \Theta_r(\Sigma, g)$ is finite.

Theorem B (L., Menezes, 2023)

Let Σ be a compact surface with boundary. If $g \in \mathcal{M}(\Sigma)$ satisfies $\Theta_r(\Sigma, g) = \Theta_r^*(\Sigma)$, then there exist a $\sigma_0(g, 2)$ -eigenfunction ϕ_0 and independent $\sigma_1(g, 2)$ -eigenfunctions ϕ_1, \ldots, ϕ_n , which induce a free boundary minimal isometric immersion $\Phi = (\phi_0, \phi_1, \ldots, \phi_n) : (\Sigma, g) \to \mathbb{B}_r^n$.

Free-boundary minimal rotational annuli

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Free-boundary minimal rotational annuli

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Otsuki (1970) and do Carmo-Dajczer (1983), described the parametrization of the family of rotational minimal surfaces in \mathbb{S}^3 :
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Otsuki (1970) and do Carmo-Dajczer (1983), described the parametrization of the family of rotational minimal surfaces in \mathbb{S}^3 : $\Phi_a : \mathbb{R} \times \mathbb{S}^1 \to \mathbb{S}^3$,

$$\Phi_{a}(s,\theta) = \left(\sqrt{\frac{1}{2} - a\cos(2s)}\cos\varphi(s), \sqrt{\frac{1}{2} - a\cos(2s)}\sin\varphi(s), \sqrt{\frac{1}{2} + a\cos(2s)}\sin\varphi(s), \sqrt{\frac{1}{2} + a\cos(2s)}\sin\theta\right),$$

where $-rac{1}{2} < a \leq 0$ is a constant and arphi(s) is given by

$$arphi(s) = \sqrt{rac{1}{4} - a^2} \int_0^s rac{1}{(rac{1}{2} - a\cos(2t))\sqrt{rac{1}{2} + a\cos(2t)}} dt.$$

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Proposition (Li-Xiong, 2018): For any $0 < r \le \frac{\pi}{2}$, there exist $-\frac{1}{2} < a \le 0$ and $s_0 \in \mathbb{R}$ such that $\Phi_a : [-s_0, s_0] \times \mathbb{S}^1 \to \mathbb{B}^3_r$ is a free boundary minimal immersion.

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Theorem C (L., Menezes, 2023)

Let Σ be an annulus and consider a free boundary minimal immersion $\Phi = (\phi_0, \dots, \phi_n) : (\Sigma, g) \to \mathbb{B}^n_r$. Suppose ϕ_j is a $\sigma_1(g, 2)$ -eigenfunction, for $j = 1, \dots, n$. Then n = 3 and Φ is one of the rotational immersions described previously.

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Remark 1: Theorem C is analogous to the uniqueness of the critical catenoid (Fraser-Schoen), as well as to results of Montiel-Ros and El Soufi-Ilias which characterize the Clifford torus and the flat equilateral torus.

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Remark 2: By Theorems B and C, if there is a smooth metric achieving $\Theta_r^*(\Sigma)$ in the case of an annulus, then the metric is induced by the immersion of a rotational free boundary minimal annulus.

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Problem: Let Σ be a compact orientable surface. Prove that there is $g \in \mathcal{M}(\Sigma)$ realizing $\Theta_r^*(\Sigma)$.

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Problem: Let Σ be a compact orientable surface. Prove that there is $g \in \mathcal{M}(\Sigma)$ realizing $\Theta_r^*(\Sigma)$.

Remark 3: Inspired by our work, Medvedev (2023) obtained analogous results for geodesics balls in \mathbb{H}^n , \mathbb{H}^n

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Lemma: The multiplicity of $\sigma_1(g, 2)$ is at most 3. Hence n = 3.

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Lemma: The multiplicity of $\sigma_1(g, 2)$ is at most 3. Hence n = 3. Recall that

$$\begin{split} & \Delta_g \, \phi_i + 2\phi_i = 0 \quad \text{in } \Sigma, \ i = 0, 1, 2, 3, \\ & \frac{\partial \phi_0}{\partial \nu} + (\tan r) \phi_0 = 0 \quad \text{on } \partial \Sigma, \\ & \frac{\partial \phi_i}{\partial \nu} - (\cot r) \phi_i = 0 \quad \text{on } \partial \Sigma, \ i = 1, 2, 3. \end{split}$$

Since $\Sigma \simeq [0,1] \times \mathbb{S}^1$, then $g = \lambda g_{\mathrm{cyl}}$, for some positive function $\lambda = \lambda(s,\theta)$. In particular, $\Delta_g = \lambda^{-1} \Delta_{\mathrm{cyl}}$ and $\nu_g = \lambda^{-\frac{1}{2}} \nu_{\mathrm{cyl}}$.

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$$\begin{split} \Delta_{g} \phi_{i} + 2\phi_{i} &= 0 \implies \Delta_{cyl} \phi_{i} + 2\lambda \phi_{i} = 0 \\ \Rightarrow \Delta_{cyl} \frac{\partial \phi_{i}}{\partial \theta} + 2 \frac{\partial \lambda}{\partial \theta} \phi_{i} + 2\lambda \frac{\partial \phi_{i}}{\partial \theta} = 0 \\ \Rightarrow \Delta_{g} \frac{\partial \Phi}{\partial \theta} + 2\lambda^{-1} \frac{\partial \lambda}{\partial \theta} \Phi + 2 \frac{\partial \Phi}{\partial \theta} = 0. \end{split}$$

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Claim: The condition $\sigma_0(g,2) = -\tan r$ and $\sigma_1(g,2) = \cot r$ implies

$$\Delta_g \frac{\partial \phi_j}{\partial \theta} + 2 \frac{\partial \phi_j}{\partial \theta} = 0 \text{ in } \Sigma.$$

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The idea is to use $\frac{\partial \phi_i}{\partial \theta}$ as test-functions for σ_1 .

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• Combining this with the previous equation we conclude that

$$\frac{\partial \lambda}{\partial \theta} \equiv \mathbf{0},$$

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i.e, the metric g is rotationally symmetric.

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Combining this with the previous equation we conclude that

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i.e, the metric g is rotationally symmetric.

 An O.D.E analysis implies that Φ is rotational in the sense of do Carmo-Dajczer-Otsuki, so Φ(Σ) is one of the annuli described before.

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Thank you!

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